## Dijkstra's Algorithm

Given a graph  $\mathcal{G} = (V, E)$ , assume  $\mathcal{G}$  has the following properties:

- 1. for each edge  $e \in E$  connecting vertices u and v, we assign an associated positive number d(u, v) referred to as the *length* of edge e but may represent any measurable quantity.
- 2. there is an *initial vertex*  $v_0$ .
- 3. the length of a path from a vertex v to the initial vertex  $v_0$  is the sum of the lengths of the path's constituent edges.
- 4. to each vertex  $v \in V$  an associated number  $\lambda(v)$  is assigned. It is initially defined such that  $\lambda(v_0) = 0$  and for all other vertices  $\lambda(v) = \infty$

## 1 Description of Algorithm

The goal of Dijkstra's algorithm is to construct for each vertex v a shortest path from v to  $v_0$ . Dijkstra's algorithm is a recursive algorithm which at each stage constructs a set S of *visited* vertices. A visited vertex  $v \in S$  has the property that among all paths from v to  $v_0$  containing only vertices in S.

- 1. there is a shortest such path whose length is then recorded as  $\lambda(v)$ .
- 2. The path itself is recorded as a sequence of vertices.

The set  $U = V \setminus S$  is referred to as the set of *unvisited vertices*. The algorithm recursively adds points from U to S.

At each iteration of the algorithm a current vertex  $v_c \in U$  is chosen. Initially the current vertex is  $v_c = v_0$ . At each iteration three things happen.

1. For each vertex  $v \in U$  that is adjacent to  $v_c$ , the length  $\lambda(v)$  of the shortest path back to  $v_0$  is newly calculated and recorded. The path itself is recorded as a sequence of vertices.

**Note that:** (1)  $\lambda(v)$  may have already been calculated in some previous iteration and (2)  $\lambda(v_c)$  will have been calculated in the previous iteration as in step 2 below. We then now calculate

$$\lambda(v) = \min\{\lambda(v), \lambda(v_c) + d(v_c, v)\}\$$

2. A new current vertex  $w \in U$  is chosen so that for every  $u \in U$ ,  $\lambda(w) \leq \lambda(u)$ .

Note that: for those unvisited vertices u that have not been adjacent to some current vertex, we have  $\lambda(v) = \infty$  - so we may restrict attention to vertices u for which  $\lambda(u)$  has already been calculated.

- 3. Preparing for the next iteration:
  - (a) move  $v_c$  in set of visited vertices renaming S as  $S \cup v_c$
  - (b) set  $v_c = w$ .

The algorithm terminates when S = V.

Alternatively, if the shortest path to a specified vertex is desired, t he algorithm may terminate when this vertex becomes *visited*.

## 2 Complexity

Assume  $\forall v \in V$ ,  $deg(v) \leq k$  for some constant k.

Assume 
$$V = \{v_0, v_1, \cdots, v_n\}$$
 has  $n + 1$  elements.

Each of the vertices will in some iteration become the current vertex  $v_c$ . For such an iteration with current vertex  $v_c$ , let  $\tau(v_c)$  be the time to calculate  $\lambda(v)$  for each vertex v adjacent to  $v_c$ . Choose a constant r such that for each current vertex  $v_c$ ,  $r \geq \tau(v_c)$ .

The time to complete this stage of the algorithm for each current vertex is thus less than r times the number of vertices - namely rn.

Next, in an arbitrary iteration there is a search among all unvisited vertices for the shortest path back to  $v_0$ . That is, a search for

 $min\{\lambda(v):v\in U\}$  - most often this is search can be restricted to those vertices  $v\in U$  that are adjacent to  $v_c$ 

If at an arbitrary iteration, U has m elements, we know this search is of complexity O(m). Thus there is a constant s such that the time to find the shortest path is is less than sm.

Thus the time to complete this iteration is less than kr + sm.

Then for all iterations the time is less than

$$(rk+sn) + (rk+s(n-1) + \dots + (rk+s) = nrk + s(n+(n-1) + \dots + 1) = nrk + s\frac{n(n+1)}{2} = \frac{s}{2}n^2 - \frac{s}{2}n + nrk = \frac{s}{2}n^2 + n(rk - \frac{s}{2}) \le n^2(\frac{s}{2} + (rk - \frac{s}{2})) = rkn^2.$$

This shows that Djikstra's algorithm has complexity at worst  $O(n^2)$ . Careful coding allows improvements.

**Example:** Consider the following diagram. The vertex a is considered to be the initial vertex and with  $\lambda(a) = 0$ . To apply the algorithm we set up a table with the vertices labelling columns and our progressive choices of current vertices labelling the rows.

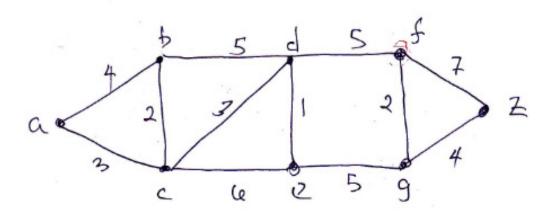


Figure 1: Dijkstra diagram

The first row of the table will indicate the starting position of the algorithm in which the various  $\lambda$  values are indicated Note that for each vertex other than a we have a value of  $\infty$ . Looking at the first row, we search for the vertex with the least  $\lambda$ . This vertex will become the

first current vertex. The vertex is of course is a. We place a in the second row in the current vertex column. We can now construct the second row of the table by examining the vertices adjacent to a, these are b and c. We record the lengths of the paths back to a, as a for a and a for a to be visited vertex, setting a for a for a to be visited vertex, setting a for a for

Next we look for the vertex adjacent to a whose distance back to a is least. This vertex is c. The new *current* vertex is thus chosen equal to c. The third row is then labeled at the left with the letter c. We now go to the next iteration looking at those vertices not in S that are adjacent to c. They are b, d and e, and for each we calculate the distance of the shortest path back to a and record the results in the table with a in the column labeled a and a in the column labeled a. We now consider a as visited and add a to a - setting a - setti

In the 3rd row we now look for the vertex with the shortest path back to a - this vertex is b - so b becomes the new *current vertex* and is laced in the first column to label the fourth row. The process now continues in the same way. The full table is shown below.

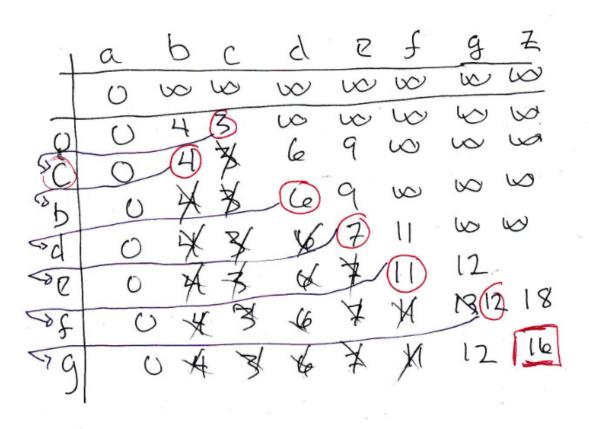


Figure 2: Dijkstra TAble