## Dijkstra's Algorithm

Given a graph $\mathcal{G}=(V, E)$, assume $\mathcal{G}$ has the following properties:

1. for each edge $e \in E$ connecting vertices $u$ and $v$, we assign an associated positive number $d(u, v)$ referred to as the length of edge $e$ - but may represent any measurable quantity.
2. there is an initial vertex $v_{0}$.
3. the length of a path from a vertex $v$ to the initial vertex $v_{0}$ is the sum of the lengths of the path's constituent edges.
4. to each vertex $v \in V$ an associated number $\lambda(v)$ is assigned.

It is initially defined such that $\lambda\left(v_{0}\right)=0$ and for all other vertices $\lambda(v)=\infty$

## 1 Description of Algorithm

The goal of Dijkstra's algorithm is to construct for each vertex $v$ a shortest path from $v$ to $v_{0}$. Dijkstra's algorithm is a recursive algorithm which at each stage constructs a set $S$ of visited vertices. A visited vertex $v \in S$ has the property that among all paths from $v$ to $v_{0}$ containing only vertices in $S$.

1. there is a shortest such path whose length is then recorded as $\lambda(v)$.
2. The path itself is recorded as a sequence of vertices.

The set $U=V \backslash S$ is referred to as the set of unvisited vertices. The algorithm recursively adds points from $U$ to $S$.

At each iteration of the algorithm a current vertex $v_{c} \in U$ is chosen. Initially the current vertex is $v_{c}=v_{0}$. At each iteration three things happen.

1. For each vertex $v \in U$ that is adjacent to $v_{c}$, the length $\lambda(v)$ of the shortest path back to $v_{0}$ is newly calculated and recorded. The path itself is recorded as a sequence of vertices.

Note that: (1) $\lambda(v)$ may have already been calculated in some previous iteration and (2) $\lambda\left(v_{c}\right)$ will have been calculated in the previous iteration as in step 2 below. We then now calculate
$\lambda(v)=\min \left\{\lambda(v), \lambda\left(v_{c}\right)+d\left(v_{c}, v\right)\right\}$
2. A new current vertex $w \in U$ is chosen so that for every $u \in U$, $\lambda(w) \leq \lambda(u)$.
Note that : for those unvisited vertices $u$ that have not been adjacent to some current vertex, we have $\lambda(v)=\infty$ - so we may restrict attention to vertices $u$ for which $\lambda(u)$ has already been calculated.
3. Preparing for the next iteration:
(a) move $v_{c}$ in set of visited vertices - renaming $S$ as $S \cup v_{c}$
(b) set $v_{c}=w$.

The algorithm terminates when $S=V$.
Alternatively, if the shortest path to a specified vertex is desired, t he algorithm may terminate when this vertex becomes visited.

## 2 Complexity

Assume $\forall v \in V, \operatorname{deg}(v) \leq k$ for some constant $k$.
Assume $V=\left\{v_{0}, v_{1}, \cdots, v_{n}\right\}$ has $n+1$ elements.
Each of the vertices will in some iteration become the current vertex $v_{c}$. For such an iteration with current vertex $v_{c}$, let $\tau\left(v_{c}\right)$ be the time to calculate $\lambda(v)$ for each vertex $v$ adjacent to $v_{c}$. Choose a constant $r$ such that for each current vertex $v_{c}, r \geq \tau\left(v_{c}\right)$.

The time to complete this stage of the algorithm for each current vertex is thus less than $r$ times the number of vertices - namely $r n$.

Next, in an arbitrary iteration there is a search among all unvisited vertices for the shortest path back to $v_{0}$. That is, a search for
$\min \{\lambda(v): v \in U\}$ - most often this is search can be restricted to those vertices $v \in U$ that are adjacent to $v_{c}$

If at an arbitrary iteration, $U$ has $m$ elements, we know this search is of complexity $O(m)$. Thus there is a constant $s$ such that the time to find the shortest path is is less than $s m$.

Thus the time to complete this iteration is less than $k r+s m$.
Then for all iterations the time is less than
$(r k+s n)+(r k+s(n-1)+\cdots+(r k+s)=n r k+s(n+(n-1)+\cdots+1)=$
$n r k+s \frac{n(n+1)}{2}=\frac{s}{2} n^{2}-\frac{s}{2} n+n r k=$
$\frac{s}{2} n^{2}+n\left(r k-\frac{s}{2}\right) \leq n^{2}\left(\frac{s}{2}+\left(r k-\frac{s}{2}\right)\right)=r k n^{2}$.
This shows that $\mathrm{D} j \mathrm{ikstra}$ 's algorithm has complexity at worst $O\left(n^{2}\right)$. Careful coding allows improvements.

Example: Consider the following diagram. The vertex $a$ is considered to be the initial vertex and with $\lambda(a)=0$. To apply the algorithm we set up a table with the vertices labelling columns and our progressive choices of current vertices labelling the rows.


Figure 1: Dijkstra diagram
The first row of the table will indicate the the starting position of the algorithm in which the various $\lambda$ values are indicated Note that for each vertex other than $a$ we have a value of $\infty$. Looking at the first row, we search for the vertex with the least $\lambda$. This vertex will become the
first current vertex. The vertex is of course is $a$. We place $a$ in the second row in the current vertex column. We can now construct the second row of the table by examining the vertices adjacent to $a$, these are $b$ and $c$. We record the lengths of the paths back to $a$, as 4 for $b$ and 3 for $c$. We now consider $a$ to be visited vertex, setting $S=\{a\}$.

Next we look for the vertex adjacent to $a$ whose distance back to $a$ is least. This vertex is $c$. The new current vertex is thus chosen equal to $c$. The third row is then labeled at the left with the letter $c$. We now go to the next iteration looking at those vertices not in $S$ that are adjacent to $c$. They are $b, d$ and $e$, and for each we calculate the distance of the shortest path back to $a$ and record the results in the table with 4 in the column labeled $b, 6$ in the column labeled $d$ and 9 in the column labeled e. We now consider $c$ as visited and add $c$ to $S$ - setting $S=\{a, c\}$. Next we calculate the shortest distance back to $a$ from each of $b, d, e$ and record the results in the fourth row. The vertex $c$ is now visited and is placed in the set $S$ - so $S=\{a, c\}$.
In the 3 rd row we now look for the vertex with the shortest path back to $a$ - this vertex is $b$ - so $b$ becomes the new current vertex and is laced in the first column to label the fourth row. The process now continues in the same way. T he full table is shown below.


Figure 2: Dijkstra TAble

