

Formula Sheet

$$\begin{aligned}
\vec{r} &= \vec{r}_0 + \vec{v}_0 t + \frac{1}{2} \vec{a} t^2 & \vec{v}_f &= \vec{v}_0 + \vec{a} t \\
v_f^2 &= v_0^2 + 2\vec{a} \cdot \Delta\vec{r} & & \\
x &= \frac{v_0^2}{g} \sin 2\theta_0 & y &= \frac{v_0^2}{2g} \sin^2 \theta_0 \\
y &= x \tan \theta_0 - \frac{g}{2v_0^2 \cos^2 \theta_0} x^2 & & \\
\vec{F} &= m\vec{a} & F &= \frac{mv^2}{r} \\
f_k &= \mu_k N & f_s &\leq \mu_s N \\
\vec{W} &= m\vec{g} & \vec{F} &= -k\vec{x} \\
K &= \frac{1}{2}mv^2 & W &= \vec{F} \cdot \Delta\vec{r} \\
\Delta K = W & & W &= \int \vec{F} \cdot \Delta\vec{r} \\
P &= \frac{dW}{dt} & \vec{F} &= -\frac{\partial U}{\partial x}\hat{i} - \frac{\partial U}{\partial y}\hat{j} - \frac{\partial U}{\partial z}\hat{k} \\
U &= \frac{1}{2}kx^2 & U &= mgh \\
\vec{p} &= m\vec{v} & \vec{F} &= \frac{d\vec{p}}{dt} \\
\vec{r}_{cm} &= \frac{\sum_i m_i \vec{r}_i}{\sum_i m_i} & v_f - v_i &= v_{er} \ln \frac{M_i}{M_f} \\
\theta(t) &= \theta_0 + \omega_0 t + \frac{1}{2}\alpha t^2 & \omega(t) &= \omega_0 + \alpha t \\
\omega^2 &= \omega_0^2 + 2\alpha\Delta\theta & W &= \tau\Delta\theta \\
W &= \int \tau d\theta & I &= \sum_i m_i r_i^2 \\
I &= \int r^2 dm & \vec{L} &= \vec{r} \times \vec{p} = I\vec{\omega} \\
\vec{\tau} &= \frac{d\vec{L}}{dt} & \vec{\tau} &= I\vec{\alpha}
\end{aligned}$$

$$I_{solid-sphere}=\frac{2}{5}MR^2$$

$$K=\frac{1}{2}I\omega^2$$

$$mv\hat{i}-Mu\hat{i}=-mv'\hat{i}+Mu'\hat{i}$$

$$\vec{F}=-\frac{GmM}{r^2}\hat{r}$$

$$T^2 = \frac{4\pi^2}{G(M_1 + M_2)} a^3$$

$$m\frac{d^2x}{dt^2}+kx=0$$

$$m\frac{d^2x}{dt^2}+b\frac{dx}{dt}+kx=0$$

$$m\frac{d^2x}{dt^2}+b\frac{dx}{dt}+kx=F_0\cos(\omega_{drive}t)$$

$$A_{drive}=\frac{F_0}{\sqrt{m^2(\omega_{drive}^2-\omega_0^2)^2+b^2\omega_{drive}^2}}$$

$$\omega_D=\sqrt{\frac{k}{m}-\left(\frac{b}{2m}\right)^2}$$

$$D(x,t)=A\sin(kx-\omega t+\phi)$$

$$v=f\lambda$$

$$\vec{F}=\frac{1}{4\pi\epsilon_0}\frac{q_1q_2}{r^2}\hat{r}$$

$$\vec{p}=q\vec{d}$$

$$U=qV$$

$$V_b-V_a=-\int_a^b\vec{E}\cdot d\vec{r}$$

$$Q=CV$$

$$I_{hollow-sphere}=\frac{2}{3}MR^2$$

$$K=\frac{1}{2}mv^2+\frac{1}{2}I\omega^2$$

$$u'=\frac{2mv+(m-M)u}{M+m}$$

$$v'=\frac{2Mu+(M-m)v}{M+m}$$

$$U=-\frac{GmM}{r}$$

$$v=\sqrt{GM\left(\frac{2}{r}-\frac{1}{a}\right)}$$

$$x(t)=A\cos(\omega t+\phi)$$

$$x(t)=Ae^{-bt/2m}\cos(\omega_D t+\phi)$$

$$x(t)=A_{drive}\cos(\omega_{drive}t+\phi_{drive})$$

$$\phi_{drive}=\tan^{-1}\left(\frac{b\,\omega_{drive}}{m(\omega_{drive}^2-\omega_0^2)}\right)$$

$$D(x,t)=A\sin(\frac{2\pi}{\lambda}x-2\pi ft+\phi)$$

$$f_r=\frac{v\pm v_r}{v\mp v_s}f_s$$

$$\vec{F}=q\vec{E}$$

$$U=\frac{Qq}{4\pi\epsilon_0 r}$$

$$\vec{E}=-\frac{\partial V}{\partial x}\hat{i}-\frac{\partial V}{\partial y}\hat{j}-\frac{\partial V}{\partial z}\hat{k}$$

$$\oint \vec{E}\cdot d\vec{A}=\frac{1}{\epsilon_0}\sum q_{enc}$$

$$C=\frac{\epsilon A}{d}$$

$$6\\$$

$$\begin{aligned}
U &= \frac{1}{2}CV^2 & u_E &= \frac{1}{2}\epsilon_0E^2 \\
C_{parallel} &= \sum_{i=1}^N C_i & \frac{1}{C_{series}} &= \sum_{i=1}^N \frac{1}{C_i} \\
R_{series} &= \sum_{i=1}^N R_i & \frac{1}{R_{parallel}} &= \sum_{i=1}^N \frac{1}{R_i} \\
I &= \frac{V}{R} & R &= \rho \frac{l}{A} \\
P &= I^2R & \vec{F} &= q\vec{v} \times \vec{B} \\
\vec{F} &= -I \int \vec{B} \times d\vec{l} & \omega &= \frac{qB}{m} \\
\vec{\mu} &= I\vec{A} & \vec{\tau} &= \vec{\mu} \times \vec{B} \\
d\vec{B} &= \frac{\mu_0}{4\pi} \frac{Id\vec{l} \times \hat{r}}{r^2} & \oint \vec{B} \cdot d\vec{l} &= \mu_0 \sum I_{enc} \\
\frac{F_{12}}{l} &= \frac{\mu_0 I_1 I_2}{2\pi R} & \mu_n &= \frac{e}{2m}\hbar n
\end{aligned}$$

Fundamental Constants

$$\begin{aligned}
G &= 6.673 \times 10^{-11} \text{ m}^3 \text{ kg}^{-1} \text{ s}^{-2} & c &= 2.997 \times 10^8 \text{ m s}^{-1} \\
N_A &= 6.022 \times 10^{23} \text{ particles mol}^{-1} & e &= 1.602 \times 10^{-19} \text{ C} \\
\epsilon_0 &= 8.854 \times 10^{-12} \text{ C}^2 \text{ N}^{-1} \text{ m}^{-2} & \mu_0 &= 4\pi \times 10^{-7} \text{ N A}^{-2} \\
\hbar &= 1.055 \times 10^{-34} \text{ J} \cdot \text{s}
\end{aligned}$$